

# ***ADAM-4500***

PC-based Communication  
Controller

## ***User's Manual***

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## **Chapter 1 General Information**

### **1.1 Introduction**

The ADAM-4500 is a fully functional standalone controller, designed for industrial automation and control, enclosed in a small package. It provides an ideal means of producing an IBM PC compatible hardware platform.

#### **Emulating Open PC environments**

The module is much like a compact computer, and includes an 80188 CPU, 256 KB Flash ROM, 256 KB SRAM, COM1, COM2, and a program download port. Its built-in ROM-DOS is an MS-DOS equivalent operating system, which provides all of the basic functions of MS-DOS except for BIOS. A user can run standard PC software and application programs, written in high level languages such as C or C++, within the ROM-DOS environment. Moreover, the module also provides free ROM memory for application downloading and free RAM memory for application operation.

#### **Built-in RS-232/RS-485 Communication Ports**

The ADAM-4500 has two communication ports to let the controller easily communicate with the other devices in your application. The COM1 port can be configured as an RS-232 or an RS-485 communication interface via the jumper setting. The COM2 port is dedicated as an RS-485 port. This unique design makes the controller suitable for use in a variety of applications.

#### **Built-in Real-time Clock and Watchdog Timer**

The controller also includes a real-time clock and a watchdog timer function. The real-time clock ensures time recording while events occur. The watchdog timer is designed to automatically reset the microprocessor when the system fails. This feature greatly reduces the level of maintenance required and makes the ADAM-4500 ideal for use in applications that require a high level of system stability.

## 1.2 Features

- ?? Built-in boot ROM-DOS to run PC programs
- ?? Free ROM/RAM memory for user's applications
- ?? 2-wire, multi-drop RS-485 networking
- ?? Communication speed up to 115.2 Kbps
- ?? RS-232/RS-485 modes (jumper selectable)
- ?? Automatic data flow control in RS-485 mode
- ?? Built-in real-time clock and watchdog timer
- ?? Easy mounting on a DIN-rail or panel
- ?? Program download cable and utility included

## 1.3 Specifications

### System

- ?? CPU: 80188-40
- ?? Flash ROM: 256 KB (170 KB free memory for users)
- ?? Operating system: Boot ROM-DOS
- ?? SRAM: 256 KB ( 234 KB free memory for users)
- ?? Timer BIOS: Yes
- ?? Real-time clock: Yes
- ?? Watchdog timer: Yes
- ?? COM1: RS-232/RS-485
- ?? COM2: RS-485
- ?? Program download port (RS-232): Tx, Rx, GND

### RS-232 Interface

- ?? Signals: TxD, RxD, RTS, CTS, DTR, DSR, DCD, RI, GND
- ?? Mode: Asynchronous full duplex, point to point
- ?? Connector: DB-9 pin
- ?? Transmission speed: up to 115.2 Kbps
- ?? Max transmission distance: 50 feet (15.2 m)

### RS-485 Interface

- ?? Signals: DATA+, DATA-
- ?? Mode: Half-duplex, multi-drop
- ?? Connector: Plug-in terminal block
- ?? Transmission speed: up to 115.2 Kbps
- ?? Max transmission distance: 1220 m (4000 feet)

### Power

- ?? Unregulated +10 to +30 V<sub>DC</sub>
- ?? Protected against power reversal
- ?? Power consumption: 2.0 W

## Mechanical

?? Case: ABS with captive mounting hardware

?? Plug-in screw terminal block:

Accepts 0.5 mm<sup>2</sup> to 2.5 mm<sup>2</sup>, 1 - #12 or 2 - #14 to #22 AWG

## Environment

?? Operating temperature: -10 to 70°C (14 to 158°F)

?? Storage temperature: -25 to 70°C (-13 to 158°F)

?? Humidity: 5 to 95 %, non-condensing

## 1.4 System Diagram

### ADAM-4500

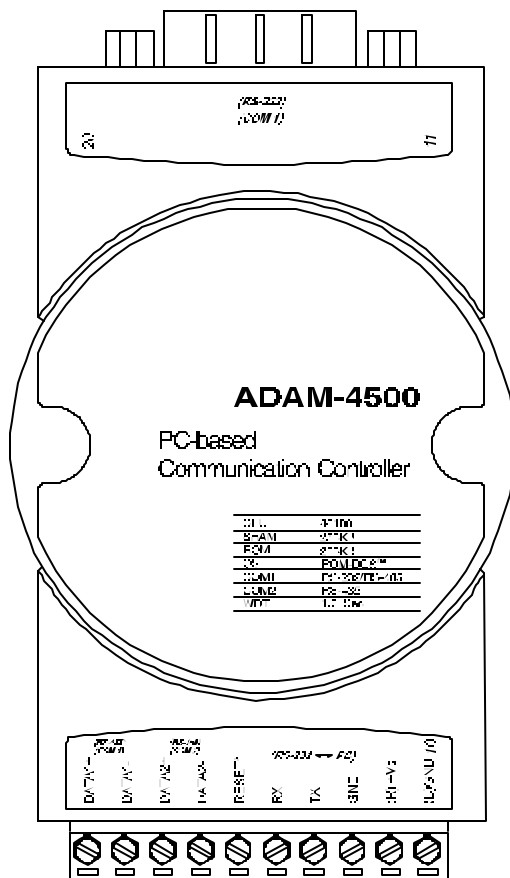


Figure 1-1: ADAM-4500 Diagram



into the ADAM-4500, can function as the host computer.

### **Power supply**

For ease of use in industrial environments, the ADAM-4500 will accept industry standard +24 V<sub>DC</sub> unregulated power. The ADAM-4500 was designed to operate using any power supply voltage between +10 and +30 V<sub>DC</sub>. Power ripples must be limited to 5 V peak to peak while the voltage in all cases must be maintained between +10 and +30 V<sub>DC</sub>.

### **Utility software**

A disk containing menu-driven utility software is provided with ADAM-4500 to help users to download programs to the ADAM-4500. The ADAM-4500 utility software is executed in an MS-DOS or compatible environment.

### **Download cable**

A customized download cable is included. A user can connect it between the COM port of a host computer and the download port of the ADAM-4500 for downloading programs.

## **2.2 Steps to Successfully Setup the System**

### **Step 1: Review the requirements**

Before you power on the ADAM-4500, make sure you have a host computer, a power supply, and the utility software and download cable.

### **Step 2: Wiring the power cables and download cable**

Connect the power cable between the power supply and the ADAM-4500. Make sure the power source is between +10 and +30 V<sub>DC</sub>.

### ***Figure 2-1: Power Supply Connections***

We advise use of the following standard colors (as indicated on the ADAM-4500) for the power cables:

+Vs (R)	Red
GND (B)	Black

Connect the download cable between the host computer and the ADAM-4500. A customized download cable is provided with the ADAM-4500, which includes a DB-9 pin connector for the connection to the host computer, and three color-coded wires for connection to the ADAM-4500 terminal block. The following figure shows how to connect the ADAM-4500 to the host computer.

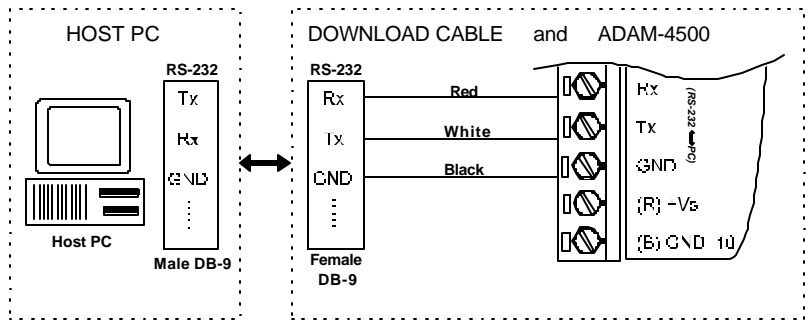


Figure 2-2: Download Cable Connections

**Step 3: Run utility software in host computer**

Together with the ADAM-4500 you will find a utility disk containing an ADAM4500.EXE file. This file is a menu-driven software utility provided for downloading user's programs. It uses a screen simulating operation of the ADAM-4500 communication controller. When the file is executed, the main screen appears, as shown in figure 2.3.

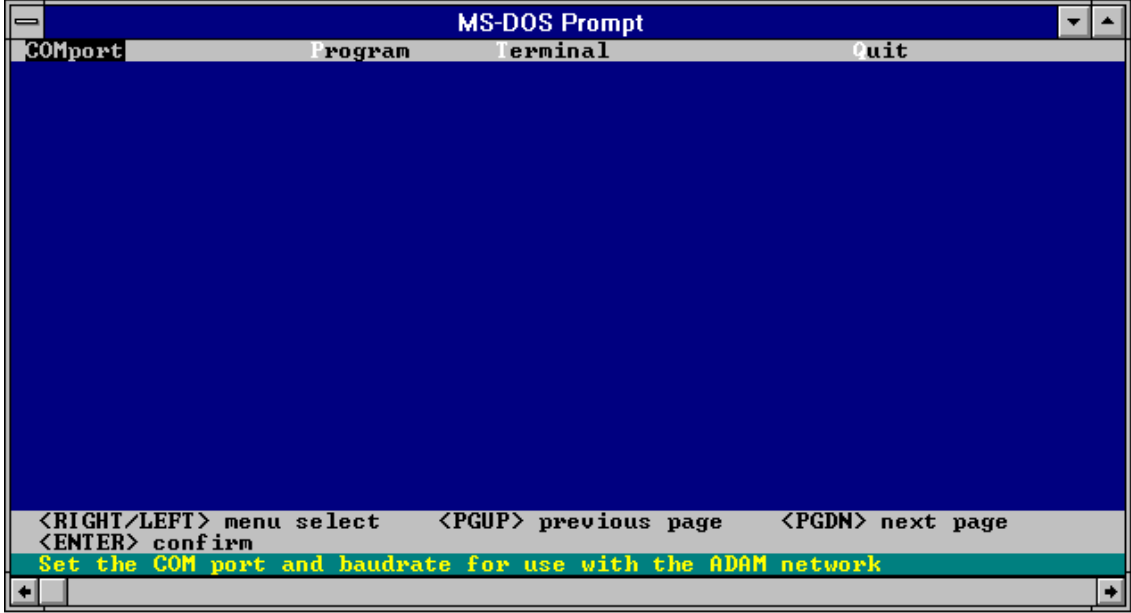


Figure 2-3: Main Screen

**Setup COM port**

First, highlight the "COMport" option on the top bar and press <enter>. The status field (shown below) will appear. Second, highlight the COM port you used to connect the ADAM-4500 to the

PC, then press <enter>. The Baudrate is set to a default value of 57600 bps and cannot be changed. The screen is as shown in figure 2.4.

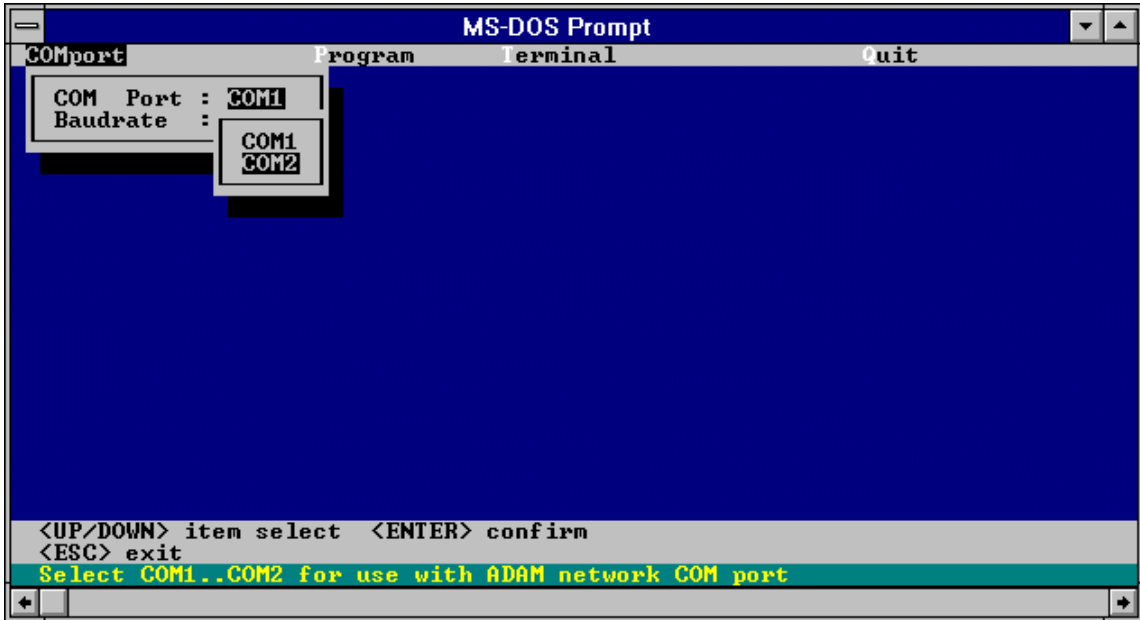
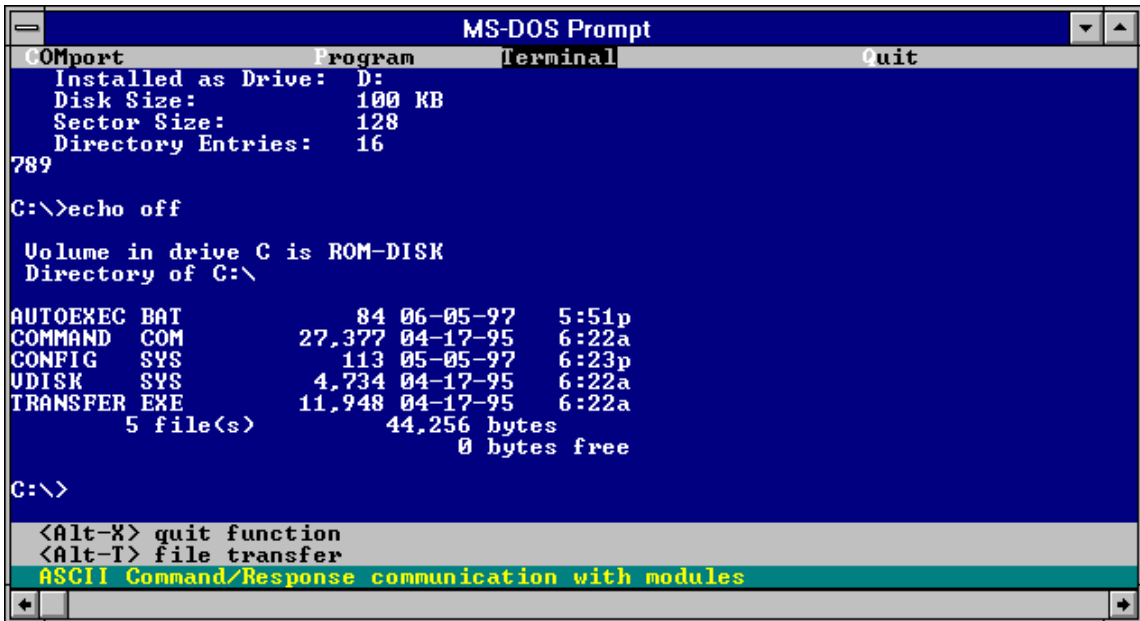


Figure 2-4: Select Communication Port

#### Step 4: Power on ADAM-4500

Highlight the "Terminal" option, then press <enter>. Power on the ADAM-4500. After 5 seconds, the screen shown in figure 2.5 will appear. The ADAM-4500 system is successfully started up.



**Figure 2-5: Emulating Screen of ADAM-4500**

### 2.3 Jumper Setting

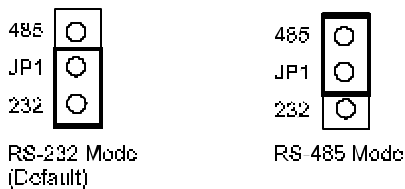
We designed the ADAM-4500 with ease-of-use in mind. It has three jumper settings. The following sections explain how to configure the module. You may want to refer to the figure below for help in identifying card components.

The following diagram shows the locations of the jumpers:

**Figure 2-6: Jumper Layout**

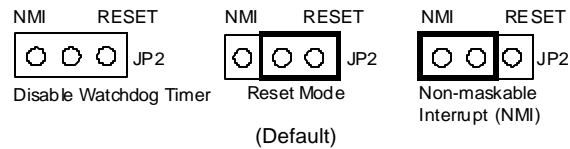
#### COM1 Port Setting (JP1)

Jumper JP1 lets you configure the COM1(3F8) port as an RS-232 or as an RS-485 interface for different applications. Jumper settings are shown below:



#### Watchdog Timer Setting (JP2)

Jumper JP2 lets you configure the watchdog timer in disable mode, reset mode or NMI (Non-maskable interrupt) mode.



#### Reset Function Setting (JP3)

Jumper JP3 enables or disables the function of the reset pin, as shown below:

### 2.4 Communication Wiring

The ADAM-4500 offers two serial ports: COM1(3F8) in RS-232 or RS-485, and COM2 (2F8) in RS-485. COM1 can be configured as an RS-232 or as an RS-485 interface via the jumper setting. This provides flexibility for communications between the controller and other devices in your application.

#### RS-232 Connection

The ADAM-4500 has a DB-9 pin connector as its RS-232 port connector. Since the connection for an RS-232 interface is not standardized, different devices implement the RS-232 connection in different ways. If you are having problems with a serial device, be sure to check the pin assignments for the connector. The following table shows the pin assignments for the ADAM-4500's RS-232 port.

Pin No.	Description
---------	-------------

1	DCD
2	RxD
3	TxD
4	DTR
5	GND
6	DSR
7	RTS
8	CTS
9	RI

**Table 2-1: Pin Assignments of RS-232 Port**

### RS-485 Connection

The RS-485 standard supports half-duplex communication. This means that just two wires are needed to both transmit and receive data. Handshaking signals (such as RTS, Request To Send) are normally used to control the direction of the data flow. A special I/O circuit in the ADAM-4500 automatically senses the direction of the data flow and switches the transmission direction. No handshaking signals are necessary. This RS-485 control is completely transparent to the user.

We recommend that shielded twisted-pair cables complying with the EIA RS-485 standard be used in the network to reduce interference. Only one set of twisted-pair cables is required to transmit both Data and RTS signals. We advise use of the following standard colors for the communication cables.

DATA +	Yellow
DATA -	Green

## Chapter 3 Programming and Downloading

This chapter explains how to program applications and download programs into the ADAM-4500 controller. Additionally, it points out limitations and concerns of which you should be aware.

### 3.1 Programming

The operating system of ADAM-4500 is ROM-DOS, an MS-DOS equivalent system. It allows users to run application programs written in assembly language as well as high level languages such as C or C++. However, there are limitations when running application programs in the ADAM-4500. In order to build successful applications, you should keep the following limitations and concerns in mind.

#### Mini BIOS Functions

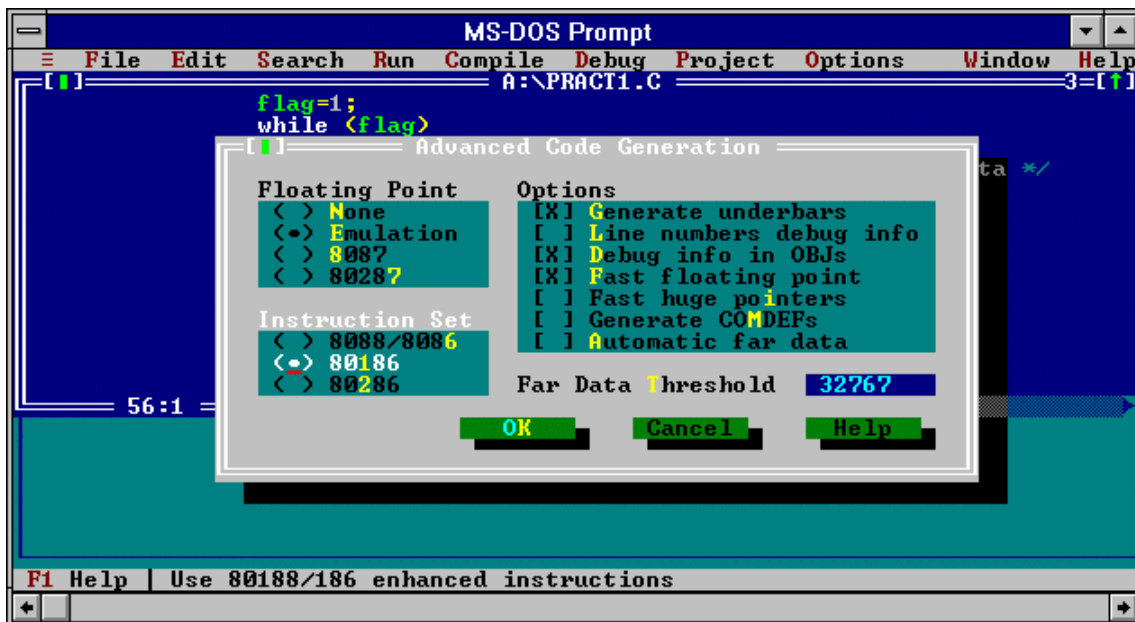
The ADAM-4500 provides only two serial communication ports for connecting peripherals, so the

mini BIOS of ADAM-4500 only provides 10 function calls. Since the user's program can not use other BIOS function calls, the ADAM-4500 may not work as intended. Additionally, certain language compilers such as QBASIC directly call BIOS functions that are not executable in ADAM-4500. The ADAM-4500 mini BIOS function calls are listed in the following table.

Function	Subfunction	Task
07h		186 or greater co-processor esc instruct
10h	0eh	TTY Clear output
11h		Get equipment
12h		Get memory size
15h	87h	Extended memory read
	88h	Extended memory size
	c0h	PS/2 or AT style A20 Gate table
16h	0	Read TTY char
	1	Get TTY status
	2	Get TTY flags
18h		Print "Failed to BOOT ROM-DOS" message
19h		Reboot system
1ah	0	Get tick count
	1	Set tick count
	2	Get real time clock
	3	Set real time clock
	4	Get date
	5	Set date
1ch		Timer tick

### Converting Program Codes

The ADAM-4500 has an 80188 CPU. Therefore, programs downloaded into its flash ROM must first be converted into 80186 or 80188 compatible code, and the floating point operation must be set to emulation mode. For example, if you were to develop your application program in Borland C, you would compile the program as indicated in the screen below.



### Figure 3-1: Converting Program Codes

#### Other Limitations

1. The ADAM-4500 does not support the standard PC function "8253". Therefore, the C language function call "delay ( )" cannot be used in ADAM-4500 applications.
2. Certain critical files are always kept in flash ROM, such as the operating system files, BIOS, and monitoring files. Aside from the storage space needed for these critical files, the ADAM-4500 has an additional 170 KB of free ROM space for downloading user applications. An additional free 234 KB of SRAM is provided for operation of applications.

#### Programming the Watchdog Timer

The ADAM-4500 is equipped with a watchdog timer function that resets the CPU or generates an interrupt if processing comes to a standstill for any reason. This feature increases system reliability in industrial standalone and unmanned environments.

If you decide to use the watchdog timer, you must write a function call to enable it. When the watchdog timer is enabled, it must be cleared by the application program at intervals of less than 1.6 seconds. If it is not cleared at the required time intervals, it will activate and reset the CPU, or generate an NMI (Non-maskable interrupt). You can use a function call in your application program to clear the watchdog timer. At the end of your program, you need an additional function call to disable the watchdog timer.

The following program shows how you might program the watchdog timer in C programs:

#### Example:

```
main ()
{
    wdt_enable();           /* enable ADAM-4500 WDT function */
    {                       /* user's function block */
        .
        .
        wdt_clear();       /* clear WDT timer */
        .
        .
    }
    wdt_disable();         /* disable ADAM-4500 WDT function */
}
```

#### Interrupt Types

Three types of interrupts may occur in the ADAM-4500. The following table shows the types of interrupts.

Interrupt Name	Interrupt Type
Non-Maskable Interrupt (NMI)	02h
COM1 Interrupt	0Ch
COM2 Interrupt	0Eh

#### Memory Mapping

The following table shows the memory mapping of the ADAM-4500 controller.

0xF8000 -- 0xFFFFF	Monitor program
0xF6C00 -- 0xF7FFF	Mini BIOS
0xCC000	Start of Application ROM Disk (about 171 K)
0xC0000	Start of ROM-DOS (about 48 K)
0x40000 -- 0xBFFFF	No Use
0x00400 -- 0x3FFFF	SRAM area
0x00000 -- 0x003FF	System area
0x003F8 -- 0x003FF	COM1
0x002F8 -- 0x002FF	COM2
0x00070 -- 0x00071	Real time clock

## 3.2 Downloading and Transferring

This section explains how to download application programs from a PC into the ADAM-4500 flash ROM and how to transfer files from a PC into ADAM-4500's SRAM.

### Install Utility Software on Host PC

A utility disk containing the following files and directories is included with each ADAM-4500.

```
. ALLFILE      <DIR>
. LIBRARY      <DIR>
. EXAMPLE      <DIR>
. ADAMMINI.HEX
. ADAM_DEM.HEX
. ROM-DOS.HEX
. DEMO-DIS.HEX
. ADAMMINI.BAT
. ADAM4500.EXE
. HEXCAT.EXE
. ROMDISK.EXE
```

Copy all the files and directories on the utility disk to the host computer hard drive.

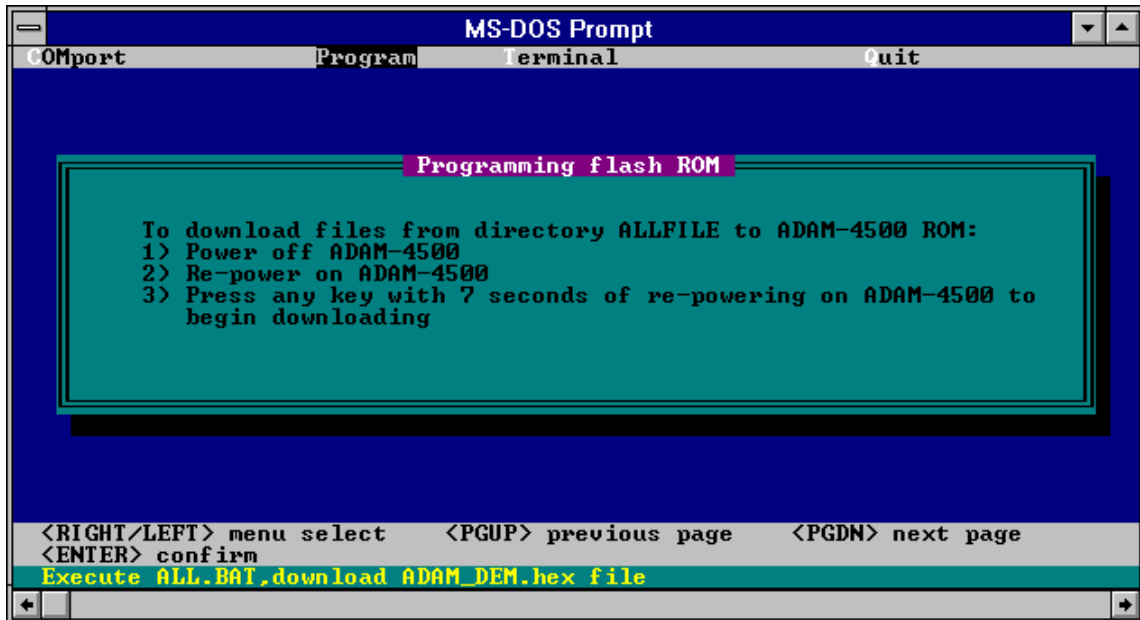
### Preparing the ALLFILE directory

Applications programs are downloaded from a host-PC to the flash ROM of the ADAM-4500 using the ADAM-4500 utility software. The ADAM-4500 utility software is first installed on a host-PC. The directory ALLFILE will be included among the contents copied from the utility software disk to the host-PC hard drive. The user must then load into ALLFILE the following required files: The application program intended for installation in ADAM-4500; COMMAND.COM; AUTOEXEC.BAT; and CONFIG.SYS. The user should make certain that AUTOEXEC.BAT contains the name of the user's application program so that the application will automatically begin executing whenever the ADAM-4500 is powered on. When downloading to the ADAM-4500's flash ROM, the utility software first clears all non-permanent files from the flash ROM, then installs all the files contained in directory ALLFILE into the flash ROM. It is therefore critical that all the required files be available in directory ALLFILE when the utility software tries to install ALLFILE's contents on the ADAM-4500's flash ROM.

### Downloading into flash ROM (ADAM-4500's C-drive)

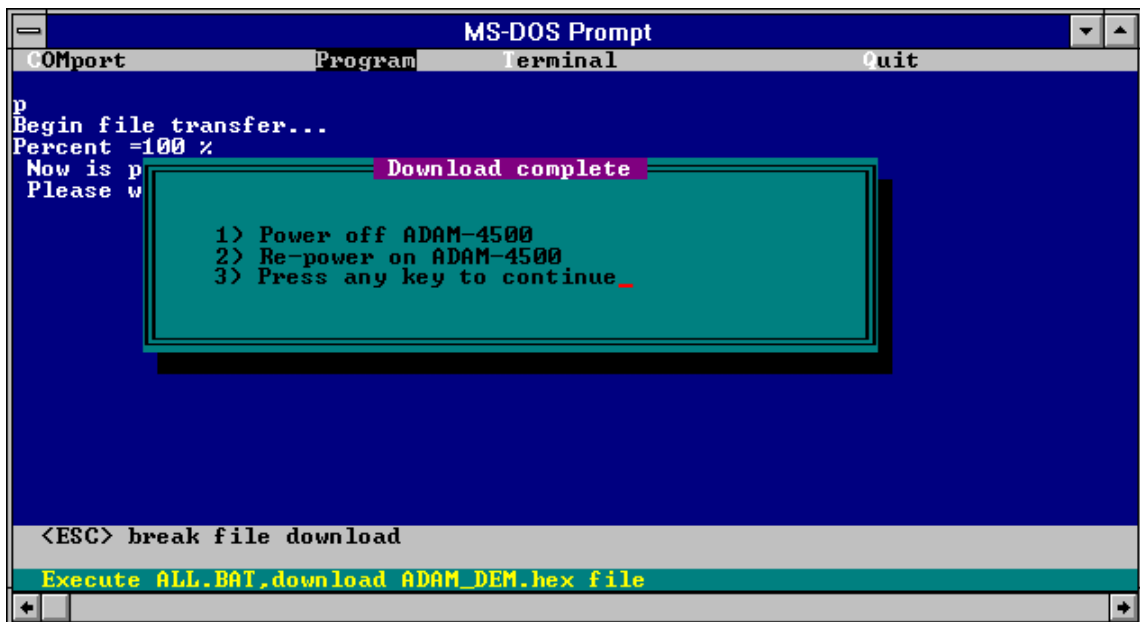
With the ADAM-4500 utility software and the directory ALLFILE, loaded with its proper contents, installed on the host-PC, you can execute the utility software. After the utility software has begun

executing, select the COMport of the host PC that has been connected to ADAM-4500. Then select "Program" from the bar menu and press <enter> to begin downloading. The screen shown in figure 3-2 will appear.



*Figure 3-2: Program downloading*

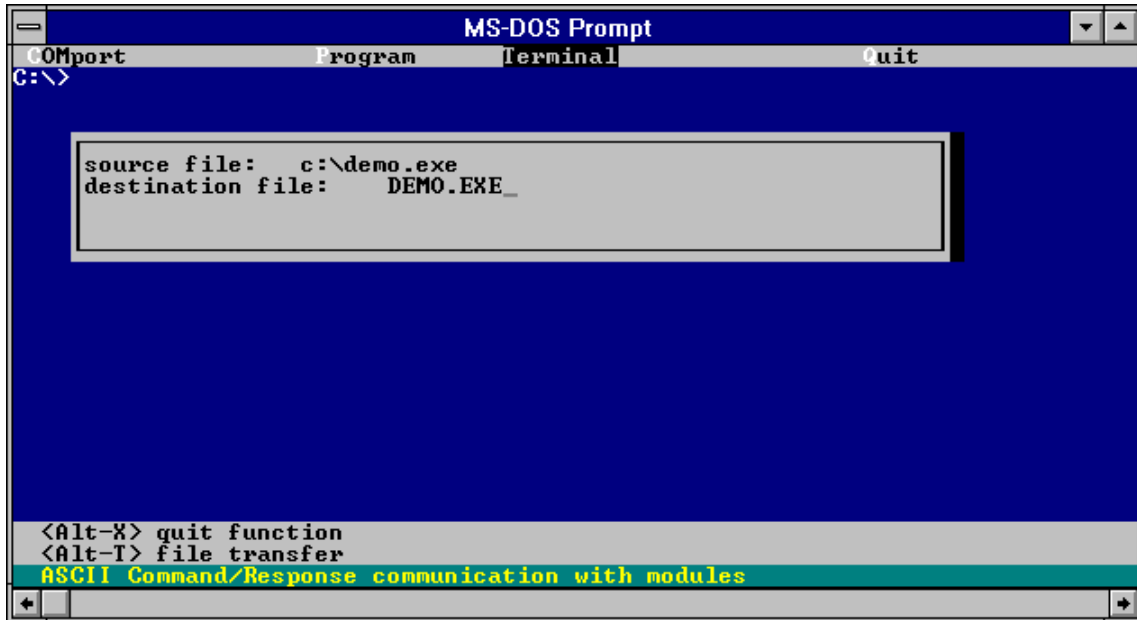
Follow the instructions shown on the screen. Power off the ADAM-4500 and then re-power on. Then press any key within 7 seconds to burn the files contained in ALLFILE into the ADAM-4500's flash ROM. After the files are successfully burned into the flash ROM, the screen in Figure 3-3 will appear. Power off and power on the ADAM-4500 once again. The ADAM-4500 controller will automatically execute the application program.



**Figure 3-3: Download Complete**

### Transferring files to SRAM (ADAM-4500's D-drive)

The ADAM-4500 provides 234 KB of free SRAM for use in program operation, and as working memory space in the event you want to test your system control logic or simulate system performance before downloading the execution code to the flash ROM. You can transfer files from a host-PC to the ADAM-4500's SRAM (D drive). Execute the utility software, select terminal mode, and press Alt-T. File transfer will begin and the screen shown in figure 3-4 will appear.



**Figure 3-4: File Transferring**

Key in the specific directory and file names you want to transfer. Press <enter> to complete the file transfer. You can check the files in D drive.

We recommend that users test new applications on their host PC before installing them in the ADAM-4500. However, the performance of the host PC may differ greatly from that of the ADAM-4500. Therefore, users may find it desirable to install an application that has been tested on the host PC into ADAM-4500's D drive for testing prior to burning it into the flash ROM. It takes less time to alter and reinstall a program into the SRAM than into the flash ROM, so using the SRAM during debugging on the ADAM-4500 may be more efficient.

## 3.3 Steps to Building a Successful Application

### Step 1: Write and simulate control logic on a PC

Connect a host-PC to the I/O device network you want to control. Write the control logic for your application on the host-PC and execute the application on the PC to verify that it works properly.

### Step 2: Connect the cables

Replace the host-PC in the control network with the ADAM-4500 and reconnect the proper power and communications cable in the network to the ADAM-4500. Connect the download cable between the host-PC and the ADAM-4500.

### **Step 3: Convert and download codes to flash ROM**

Within the host computer, convert the application program into 80186 or 80188 compatible code. Create an AUTOEXEC.BAT file for the application program and write the application program's name in the AUTOEXEC.BAT file. Also create COMMAND.COM and CONFIG.SYS files for the application program. Load the ADAM-4500 utility software into the host-PC. Load the converted application program and the files AUTOEXEC.BAT, COMMAND.COM, and CONFIG.SYS into directory ALLFILE. Execute the utility software to download the contents of ALLFILE into the ADAM-4500 flash ROM.

### **Step 4: Power on ADAM-4500 to complete the application**

After all the files in directory ALLFILE have been completely transferred to the flash ROM, re-power on the ADAM-4500.

## **Chapter 4 Function Library**

The ADAM-4500 is packaged with a utility disk that contains a directory called LIBRARY. This directory contains a number of function calls that enable a user to efficiently write applications for ADAM-4500. The library supports both Turbo C 2.0 and Microsoft C 6.0 version programming languages.

The "LIBRARY" directory contains the following two sub-directories:

. TC20	Library for Turbo C 2.0 version
. MSC60	Library for Microsoft C 6.0 version

### **Function Library for Turbo C**

The TC20 directory contains the following files:

ADAM4500.H	Declaration file
4500L.LIB	Library file for compiling large mode
4500S.LIB	Library file for compiling small mode

### **Function Library for Microsoft C**

The MSC60 directory contains the following files:

ADAM4500.H	Declaration file
4500L.LIB	Library file for compiler large mode
4500C.LIB	Library file for compiler compact mode
4500M.LIB	Library file for compiler medium mode
4500S.LIB	Library file for compiler small mode

The function calls included in the directory LIBRARY are described in the following pages.

**comm\_init**

**Syntax:**

```
int comm_init(int buf_size)
```

**Function description:**

Initializes the communication port and interrupt routine before other function calls use the communication port.

**Parameter**

```
int buf_size
```

**Description**

Sets the buffer size of every communication port for storage of received data. The unit of size is bytes.

**Return:**

Returns a 1 if command succeeds. Returns a 0 if it fails.

**comm\_exit****Syntax:**

```
int comm_exit()
```

**Function Description:**

If a user calls the **comm\_init** function, the user must call this function to release the communication port before the user's program terminates.

**Return:**

Returns a 1 if command succeeds. Return a 0 if it fails.

**comm\_open****Syntax:**

```
int comm_open(unsigned char port, unsigned long baud, int parity, int data, int stop, int cmd_type)
```

**Function Description:**

To open a communication port for user to send and receive data.

**Parameter**

```
unsigned char port
```

**Description**

Specifies communication port.

1: COM1 port

2: COM2 port

```
unsigned long baud
```

Baud rate setting. The eight allowable baud rates are: 1200, 2400, 4800, 9600, 19200, 38400, 57600, and 115200. Sized in bps (bits per second).

```
int parity
```

Parity setting.

0: no parity, 1: odd, 2: even

```
int data
```

Data bits setting. There are four allowable data lengths: 8, 7, 6, and 5. Sized in bit units.

int stop	Stop bits setting 1, 2 (stop bit = 1 is for data bits = 5,6,7, or 8) (stop bit = 2 is for data bits = 6,7, or 8) For details, refer to RS-232 chip set data book
int cmd_type	Received data format setting. 0: single byte mode. The data format is a single byte character. User can use <b>comm_get_rec_datas</b> to receive single byte data.  1: command mode. The data format is a string. User can use <b>comm_get_rec_str</b> to receive string data.

**Return:**

Returns a 1 if command succeeds. Returns a 0 if it fails.

## comm\_send

**Syntax:**

int comm\_send(unsigned char c, unsigned char port)

**Function Description:**

To send a character to a specified communication port.

**Parameter**

unsigned char c

**Description**

Represents character to be sent.

unsigned char port

or

Specifies communication port to which character is sent (COM1 COM2)

1: COM1 port

2: COM2 port

**Return:**

Returns a 1 if command succeeds. Returns a 0 if it fails.

## comm\_get\_rec\_datas

**Syntax:**

int comm\_get\_rec\_datas(unsigned \*length, unsigned char \*\*data, unsigned char port)

**Function Description :**

The function is called to receive a single byte of data. The function call returns a success flag if the communication port receives any data. The function call returns a failed flag if the buffer of the communication port is empty. The length of the data packet received (in bytes) is stored in parameter "length". The contents of the data packet received are stored in parameter "data".

**Parameter**

unsigned \*length

**Description**

Returns the length of the received data

unsigned char \*\*data

Returns the received data contents. User must first allocate a

data buffer ( Use **comm\_int** function call ). Before exiting program, user must free this buffer ( Use **comm\_exit** function call ).

unsigned char port                      Specifies communication port (COM1 or COM2)  
1: COM1 port  
2: COM2 port

**Return:**  
Returns a 1 if command succeeds. Returns a 0 if it fails.

## **comm\_get\_rec\_str**

**Syntax:**  
int comm\_get\_rec\_str(unsigned char \*\*data, unsigned char port)

**Function Description:**  
This function call is employed to received string data. The function call returns a success flag if the communication port receives string data ( terminal character is 0x0d) . The function call returns a fail flag if the buffer of the communication port is empty.

<b>Parameter</b>	<b>Description</b>
unsigned char **data	Returns the received string contents. User must first allocate a data buffer (Use <b>comm_int</b> function call). Before exiting program, user must free this buffer (Use <b>comm_exit</b> function call).
unsigned char port	Specifies communication port (COM1 or COM2) 1: COM1 port 2: COM2 port

**Return:**  
Returns a 1 if command succeeds. Returns a 0 if it fails.

## **led\_init**

**Syntax:**  
void led\_init()

**Function Description:**  
This function must be called to initialize the ADAM-4500's LED before a user's program can control the LED.

## **led**

**Syntax:**  
void led(int type)

**Function Description:**

LED ON/OFF control

<b>Parameter</b>	<b>Description</b>
int type	0: LED OFF 1: LED ON

**wdt\_enable****Syntax:**

wdt\_enable()

**Function Description:**

This function enables the watchdog timer function. After a user calls this function, the user must call the `wdt_clear()` function to refresh the watchdog timer; otherwise the CPU resets, or a non-maskable interrupt is generated.

**wdt\_clear****Syntax:**

wdt\_clear()

**Function Description:**

This function refreshes the watchdog timer, thereby avoiding the resetting of the CPU or the generation of a non-maskable interrupt.

**wdt\_disable****Syntax:**

wdt\_disable()

**Function Description:**

This function disables the watchdog timer function.

## Appendix A Register Structure

This appendix gives a short description of each of the ADAM-4500's registers. For more information please refer to the data book for the STARTECH 16C550 UART chip.

All registers are one byte in length. Bit 0 is the least significant bit, and bit 7 is the most significant bit. The address of each register is specified as an offset from the port base address (BASE), COM1 is 3F8h and COM2 is 2F8h.

DLAB is the "Divisor Latch Access Bit", bit 7 of BASE+3.

BASE+0 Receiver buffer register when DLAB=0 and the operation is a read.  
 BASE+0 Transmitter holding register when DLAB=0 and the operation is a write.  
 BASE+0 Divisor latch bits 0 - 7 when DLAB=1  
 BASE+1 Divisor latch bits 8-15 when DLAB=1.

The two bytes BASE+0 and BASE+1 together form a 16-bit number, the divisor, which determines the baud rate. Set the divisor as follows:

Baud rate	Divisor	Baud rate	Divisor
50	2304	2400	48
75	1536	3600	32
110	1047	4800	24
133.5	857	7200	16
150	768	9600	12
300	384	19200	6
600	192	38400	3
1200	96	56000	2
1800	64	115200	1
2000	58		

BASE+1 Interrupt Status Register (ISR) when DLAB=0  
 bit 0 Enable received-data-available interrupt  
 bit 1 Enable transmitter-holding-register-empty interrupt  
 bit 2 Enable receiver-line-status interrupt  
 bit 3 Enable modem-status interrupt

BASE+2 FIFO Control Register (FCR)  
 bit 0 Enable transmit and receive FIFOs  
 bit 1 Clear contents of receive FIFO  
 bit 2 Clear contents of transmit FIFO  
 bits 6-7 Set trigger level for receiver FIFO interrupt

Bit 7	Bit 6	FIFO trigger level
0	0	01
0	1	04
1	0	08
1	1	14

BASE+3 Line Control Register (LCR)  
 bit 0 Word length select bit 0  
 bit 1 Word length select bit 1

Bit 1	Bit 0	Word length (bits)
0	0	5
0	1	6
1	0	7
1	1	8

bit 2 Number of stop bits  
 bit 3 Parity enable  
 bit 4 Even parity select  
 bit 5 Stick parity  
 bit 6 Set break  
 bit 7 Divisor Latch Access Bit (DLAB)

BASE+4	Modem Control Register (MCR)
	bit 0 DTR
	bit 1 RTS
BASE+5	Line Status Register (LSR)
	bit 0 Receiver data ready
	bit 1 Overrun error
	bit 2 Parity error
	bit 3 Framing error
	bit 4 Break interrupt
	bit 5 Transmitter holding register empty
	bit 6 Transmitter shift register empty
	bit 7 At least one parity error, framing error or break indication
in the	FIFO
BASE+6	Modem Status Register (MSR)
	bit 0 Delta CTS
	bit 1 Delta DSR
	bit 2 Trailing edge ring indicator
	bit 3 Delta received line signal detect
	bit 4 CTS
	bit 5 DSR
	bit 6 RI
	bit 7 Received line signal detect
BASE+7	Temporary data register

## Appendix B Safety Instructions

1. Please read these safety instructions carefully.
2. Please keep this User's Manual for later reference.
3. Please disconnect this equipment from AC outlet before cleaning. Don't use liquid or sprayed detergent for cleaning. Use moisture sheet or cloth for cleaning.
4. For pluggable equipment, the socket-outlet shall be installed near the equipment and shall be easily accessible.
5. Please keep this equipment from humidity.
6. Lay this equipment on a reliable surface when install. A drop or fall could cause injury.
7. The openings on the enclosure are for air convection hence protect the equipment from overheating. DO NOT COVER THE OPENINGS.
8. Make sure the voltage of the power source when connect the equipment to the power outlet.
9. Place the power cord such a way that people can not step on it. Do not place anything over the power cord.
10. All cautions and warnings on the equipment should be noted.
11. If the equipment is not used for a long time, disconnect the equipment from mains to avoid being damaged by transient overvoltage.
12. Never pour any liquid into opening, this could cause fire or electrical shock.
13. Never open the equipment. For safety reason, the equipment should only be opened by qualified service personnel.
14. If one of the following situations arises, get the equipment checked by a service personnel:
  - a. The power cord or plug is damaged.
  - b. Liquid has penetrated into the equipment.
  - c. The equipment has been exposed to moisture.
  - d. The equipment does not work well or you can not get it to work according to user's manual.

- e. The equipment has dropped and damaged.
- f. If the equipment has obvious sign of breakage.

15. DO NOT LEAVE THIS EQUIPMENT IN AN ENVIRONMENT UNCONDITIONED, STORAGE TEMPERATURE BELOW -20° C (-4° F) OR ABOVE 60°C (140°F), IT MAY DAMAGE THE EQUIPMENT.

The sound pressure level at the operators position according to IEC 704-1:1982 is equal to or less than 70dB(A).

DISCLAIMER: This set of instructions is provided according to IEC 704-1. Advantech disclaims all responsibility for the accuracy of any statements contained therein.

## Wichtige Sicherheitshinweise

1. Bitte lesen sie sich diese Hinweise sorgfältig durch.
  2. Heben Sie diese Anleitung für den späteren Gebrauch auf.
  3. Vor jedem Reinigen ist das Gerät vom Stromnetz zu trennen. Verwenden Sie keine Flüssig- oder Aerosolreiniger. Am besten dient ein angefeuchtetes Tuch zur Reinigung.
  4. Die Netzanschlusssteckdose soll nahe dem Gerät angebracht und leicht zugänglich sein.
  5. Das Gerät ist vor Feuchtigkeit zu schützen.
  6. Bei der Aufstellung des Gerätes ist auf sicheren Stand zu achten. Ein Kippen oder Fallen könnte Verletzungen hervorrufen.
  7. Die Belüftungsöffnungen dienen zur Luftzirkulation die das Gerät vor Überhitzung schützt. Sorgen Sie dafür, daß diese Öffnungen nicht abgedeckt werden.
  8. Beachten Sie beim Anschluß an das Stromnetz die Anschlußwerte.
  9. Verlegen Sie die Netzanschlusbleitung so, daß niemand darüber fallen kann. Es sollte auch nichts auf der Leitung abgestellt werden.
  10. Alle Hinweise und Warnungen die sich an Geräten befinden sind zu beachten.
  11. Wird das Gerät über einen längeren Zeitraum nicht benutzt, sollten Sie es vom Stromnetz trennen. Somit wird im Falle einer Überspannung eine Beschädigung vermieden.
  12. Durch die Lüftungsöffnungen dürfen niemals Gegenstände oder Flüssigkeiten in das Gerät gelangen. Dies könnte einen Brand bzw. elektrischen Schlag auslösen.
  13. Öffnen Sie niemals das Gerät. Das Gerät darf aus Gründen der elektrischen Sicherheit nur von autorisiertem Servicepersonal geöffnet werden.
  14. Wenn folgende Situationen auftreten ist das Gerät vom Stromnetz zu trennen und von einer qualifizierten Servicestelle zu überprüfen:
    - a - Netzkabel oder Netzstecker sind beschädigt.
    - b - Flüssigkeit ist in das Gerät eingedrungen.
    - c - Das Gerät war Feuchtigkeit ausgesetzt.
    - d - Wenn das Gerät nicht der Bedienungsanleitung entsprechend funktioniert oder Sie mit Hilfe dieser Anleitung keine Verbesserung erzielen.
    - e - Das Gerät ist gefallen und/oder das Gehäuse ist beschädigt.
    - f - Wenn das Gerät deutliche Anzeichen eines Defektes aufweist.
- Der arbeitsplatzbezogene Schalldruckpegel nach DIN 45 635 Teil 1000 beträgt 70dB(A) oder weniger.

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